
NON-RIEMANNIAN GRAVITY FROM DFT

BASED ON 2012.07765 WITH U. GURSOY, N. ZINNATO AND S. VERMA

NON-RIEMANNIAN GEOMETRY

➤ **Covariantization of non-Lorentzian symmetries**

➤ **We will focus on three particular examples of non-riemannian geometries**

1. Torsional Newton Cartan (Non-relativistic with Galilean symmetry)

2. Carroll (Ultra relativistic with Carroll symmetry)

3. String Newton Cartan (Non-relativistic with String-Galilean symmetry)

NON-RIEMANNIAN GRAVITY

➤ **NR-geometries have notions of distance (degenerate metric), curvature, etc**

For SNC there are two temporal directions

$h^{\mu\nu}$	τ_μ			
spatial degenerate Inverse metric	Clock one form (temporal vielbein)	$h^{\mu\nu}\tau_\mu = 0$		$\{\Gamma_{\mu\nu}^\lambda, R^\lambda_{\rho\mu\nu}, \Gamma_{[\mu\nu]}^\lambda\}$
		$h_{\mu\nu}v^\nu = 0$	$h_{\mu\rho}h^{\rho\nu} - \tau_\mu v^\nu = \delta_\nu^\mu$	
$h_{\mu\nu}$	v^μ			
spatial degenerate metric	Inverse temporal vielbein	$\tau_\mu v^\mu = -1$		Parallel transport, curvature And torsion

➤ **We want to look at the dynamics of these NR geometric objects: equations of motion and possibly action principles. Many possible applications.**

PATHS TO NON-RIEMANNIAN GRAVITY

- **Using symmetries** [1505.05011 Hartong](#), [1807.04765 Hansen et al.](#)
 - **NR limits of Lorentz action/equations of motion**
 - Ex 1. $c \rightarrow \infty$ or $c \rightarrow 0$ limits** [1810.09387 Bergshoeff et al.](#) , [1604.08054 Hartong et al.](#)
 - Ex 2. $1/c$ expansion** [1703.03459 Van den Bleeken](#), [2001.10277 Hansen et al.](#) , [2102.06974 Bergshoeff et al.](#)
 - **Embedding in known models**
 - Ex 1. Null reduction**
 - Ex2. DFT (Doubled gravity)** [2012.07765 Gallegos et al.](#)
 - **Other approaches**
 - Beta functions** [1905.07315 Gomis et al.](#) , [1906.01607 Gallegos et al.](#)
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WHY DFT?

- **There exist a relation between T-duality, null isometries and non-riemannian theories**

1806.06071 Bergshoeff et al.

- **DFT provides a T-duality invariant formulation of supergravity**

0904.4664 Hull & Zwiebach, 1109.1782 Zwiebach, many more

- **DFT is a natural playground to study these theories in a unified way**

1508.01121 Moon Ko et al. , 1707.03713 Morand and Park

NS-NS Supergravity
(g, B, ϕ)

T-duality invariance



Double Field Theory

Contact with NR
Geometry



**Non-Riemannian
Parametrization**

Stands by itself



Doubled Gravity



**NS-NS Non-Riemannian
Supergravity**
(h, τ, B, \dots)



Equations of motion
and "action principles"



DOUBLED GRAVITY

NS-NS SUPERGRAVITY

- **The basic fields are (g, B, ϕ) and are subject to the equations of motion**

$$R_{\mu\nu} + 2\nabla_\mu \nabla_\nu \phi - \frac{1}{4} H_\mu^{\rho\sigma} H_{\nu\rho\sigma} = 0$$
$$\nabla_\rho H^{\rho\mu\nu} - 2\nabla_\rho \phi H^{\rho\mu\nu} = 0$$

- **The equations of motion can be derived from the action**

$$S = \int d^d x e \left[R + 4\nabla_\mu \phi \nabla^\mu \phi - \frac{1}{12} H^{\mu\nu\rho} H_{\mu\nu\rho} \right]$$

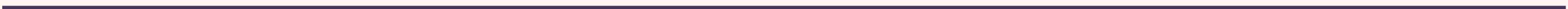


NS-NS SUPERGRAVITY AND T-DUALITY

- **The D-dimensional theory exhibits a T-duality symmetry (large compact dimensions are dual to small compact dimensions)**
- **This symmetry is geometrized into an $O(D,D)$ symmetry.**
- **The elements of $O(D,D)$ can be defined as the set of $2D \times 2D$ matrices \mathcal{H} that preserve the $O(D,D)$ invariant metric η_{MN}**

$$\mathcal{H}_M{}^P \eta_{PQ} \mathcal{H}^Q{}_N = \eta_{MN}$$

$$\eta_{MN} = \begin{pmatrix} 0 & \delta_\nu^\mu \\ \delta_\mu^\nu & 0 \end{pmatrix}$$



NS-NS SUPERGRAVITY AND T-DUALITY

- **The theory should be rewritten in terms of $O(D,D)$ covariant objects**
- **We should double the coordinates** $X^M = (X^\mu, \tilde{X}_\nu)$
- **To recover NS-NS gravity we need to impose independence of dual coordinates**
- **(g,B) are captured by a single $O(D,D)$ tensor and ϕ is captured by a tensor density d**

$$\mathcal{H} = \begin{pmatrix} g_{\mu\nu} - B_{\mu\rho}g^{\rho\sigma}B_{\sigma\nu} & -g^{\nu\rho}B_{\rho\mu} \\ -g^{\mu\rho}B_{\rho\nu} & g^{\mu\nu} \end{pmatrix}$$

Generalized Metric

$$e^{-2d} = e^{-2\phi} \sqrt{-g}$$

Generalized Dilaton

A DFT FORMULATION OF GRAVITY

1003.5027. Hohm et al. 1006.4823 Hohm et al.

➤ We can rewrite the action in terms of $O(D,D)$ objects

$$S_{\text{DFT}} = \int d^D X d^D \tilde{X} e^{-2d} \mathcal{R} \quad \text{Reduces to NS-NS action}$$

DFT Ricci Scalar

$$\begin{aligned} \mathcal{R} = & 4\mathcal{H}^{MN} \partial_M \partial_N d - \partial_M \partial_N \mathcal{H}^{MN} - 4\mathcal{H}^{MN} \partial_M d \partial_N d + 4\partial_M \mathcal{H}^{MN} \partial_N d \\ & + \frac{1}{8} \mathcal{H}^{MN} \partial_M \mathcal{H}^{KL} \partial_N \mathcal{H}_{KL} - \frac{1}{2} \mathcal{H}^{MN} \partial_M \mathcal{H}^{KL} \partial_K \mathcal{H}_{NL} \end{aligned}$$

➤ From the variation of the generalized metric we find the equations of motion

$$\text{DFT Ricci Tensor } \mathcal{R}_{MN} = 0$$

$$\mathcal{R} = 0$$

A DFT FORMULATION OF GRAVITY

- **The same action can be constructed in the same way the Einstein-Hilbert action is constructed by using $O(D,D)$ symmetry instead of Lorentz symmetry.**

1105.6294 Jeon et al.

- **A notion of generalized diffeomorphisms needs to be introduced and from there parallel transport, curvature, torsion can be constructed.**

- **DFT action stands on its own without referencing its NS-NS origins.**
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$$\mathcal{H} = \begin{pmatrix} g_{\mu\nu} - B_{\mu\rho}g^{\rho\sigma}B_{\sigma\nu} & -g^{\nu\rho}B_{\rho\mu} \\ -g^{\mu\rho}B_{\rho\nu} & g^{\mu\nu} \end{pmatrix}$$

NS-NS Supergravity
(g,B,ϕ)



Double Field Theory



Doubled Gravity

$$S_{\text{DFT}} = \int d^D X d^D \tilde{X} e^{-2d} \mathcal{R}$$

$$\begin{aligned} \mathcal{R} = & 4\mathcal{H}^{MN} \partial_M \partial_N d - \partial_M \partial_N \mathcal{H}^{MN} - 4\mathcal{H}^{MN} \partial_M d \partial_N d + 4\partial_M \mathcal{H}^{MN} \partial_N d \\ & + \frac{1}{8} \mathcal{H}^{MN} \partial_M \mathcal{H}^{KL} \partial_N \mathcal{H}_{KL} - \frac{1}{2} \mathcal{H}^{MN} \partial_M \mathcal{H}^{KL} \partial_K \mathcal{H}_{NL} \end{aligned}$$

DFT AND NON-RIEMANNIAN GEOMETRY

GENERAL PARAMETRIZATION OF THE GENERALIZED METRIC

1707.03713 Morand and Park

- **The Riemann parametrization of the generalized metric is not the most general one**

$$\mathcal{H} = \begin{pmatrix} g_{\mu\nu} - B_{\mu\rho} g^{\rho\sigma} B_{\sigma\nu} & -g^{\nu\rho} B_{\rho\mu} \\ -g^{\mu\rho} B_{\rho\nu} & g^{\mu\nu} \end{pmatrix}$$

- **The most general parametrization has been worked out to be of the form**

$$\mathcal{H}_{MN} = \begin{pmatrix} K_{\mu\nu} - \mathcal{B}_{\mu\rho} H^{\rho\sigma} \mathcal{B}_{\sigma\nu} + 2 (Z^T)_{(\mu}^{\rho} \mathcal{B}_{\nu)\rho} & -H^{\nu\rho} \mathcal{B}_{\rho\mu} + Z_{\mu}^{\nu} \\ -H^{\mu\rho} \mathcal{B}_{\rho\nu} + Z_{\mu}^{\nu} & H^{\mu\nu} \end{pmatrix} \quad Z_{\mu}^{\nu} = y_i^{\nu} x_{\mu}^i - \bar{y}_{\bar{I}}^{\nu} \bar{x}_{\mu}^{\bar{i}}$$

$$\{0 \leq i \leq n, 0 \leq \bar{i} \leq \bar{n}\} \quad \text{s.t.} \quad n + \bar{n} < D$$

- **There are two symmetric tensors ($\mathbf{K}_{\mu\nu}, \mathbf{H}^{\mu\nu}$), an antisymmetric two form $\mathbf{B}_{\mu\nu}$, and four sets of vectors $\{\mathbf{x}, \bar{\mathbf{x}}, \mathbf{y}, \bar{\mathbf{y}}\}$.**

GENERAL PARAMETRIZATION OF THE GENERALIZED METRIC

1707.03713 Morand and Park

- The parametrization is characterized by the pair of integers (n, \bar{n}) , their sum is equal to the number of null eigenvectors $\{x, \bar{x}\}$ and $\{y, \bar{y}\}$ of the symmetric tensors

$$H^{\mu\nu} x_\nu^i = H^{\mu\nu} \bar{x}_\nu^{\bar{i}} = 0 \qquad K_{\mu\nu} y_j^\nu = K_{\mu\nu} \bar{y}_j^{\bar{\nu}} = 0$$

- The difference of these integers is an $O(D, D)$ invariant

$$\mathcal{H}_M^M = 2(n - \bar{n})$$

- The fields are subject to the completeness relation

$$H^{\mu\rho} K_{\rho\nu} + y_i^\mu x_\nu^i + \bar{y}_i^\mu \bar{x}_\nu^{\bar{i}} = \delta_\nu^\mu$$

$$\{y_i^\mu x_\mu^j = \delta_i^j, \bar{y}_i^\mu \bar{x}_\mu^{\bar{j}} = \delta_i^{\bar{j}}, y_i^\mu \bar{x}_\mu^{\bar{j}} = \bar{y}_i^\mu x_\mu^j = 0\}$$

- These fields are reminiscent of the usual TNC or SNC metrics
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SYMMETRIES OF THE PARAMETRIZATION

1707.03713 Morand and Park

- **The parametrization has a $GL(n) \times GL(\bar{n})$ local symmetry and a generalized Milne shift symmetry**

$$(y_i^\mu)' = y_i^\mu + V_i^\mu$$

$$(\bar{y}_{\bar{i}}^\mu)' = \bar{y}_{\bar{i}}^\mu + \bar{V}_{\bar{i}}^\mu$$

$$(K_{\mu\nu})' = K_{\mu\nu} - 2x_{(\mu}^i K_{\nu)\rho} V_i^\rho - 2\bar{x}_{(\mu}^{\bar{i}} K_{\nu)\rho} \bar{V}_{\bar{i}}^\rho + (x_\mu^i V_{\rho i} + \bar{x}_\mu^{\bar{i}} \bar{V}_{\rho \bar{i}}) (x_\nu^i V_i^\rho + \bar{x}_\nu^{\bar{i}} \bar{V}_{\bar{i}}^\rho)$$

$$(\mathcal{B}_{\mu\nu})' = \mathcal{B}_{\mu\nu} - 2x_{[\mu}^i V_{\nu]i} + 2\bar{x}_{[\mu}^{\bar{i}} \bar{V}_{\nu]\bar{i}} + 2x_{[\mu}^i \bar{x}_{\nu]}^{\bar{j}} (y_i^\rho \bar{V}_{\rho \bar{j}} + \bar{y}_{\bar{j}}^\rho V_{\rho i} + V_{\rho i} \bar{V}_{\bar{j}}^\rho)$$

- **This shift symmetry will reduce to the known Galilean and Carroll boosts**
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SOME EXAMPLES

- **The (0,1) or (1,0) theory can be identified with TNC (without the U(1) central extension)**

$$H^{\mu\nu} = h^{\mu\nu} \quad \{x_\mu^1 = \tau_\mu, \bar{x}_\mu^{\bar{i}} = 0\}$$

$$K_{\mu\nu} = h_{\mu\nu} \quad \{y_1^\mu = -v_\mu, \bar{y}_i^\mu = 0\}$$

- **The (D-1,0) or (0,D-1) theory can be identified with Carroll**

$$H^{\mu\nu} = v^\mu v^\nu \quad \{x_\mu^{i=1,\dots,D} = e_\mu^a, \bar{x}_\mu^{\bar{i}} = 0\} \quad e_\mu^a e_\nu^b \delta_{ab} = h_{\mu\nu}$$

$$K_{\mu\nu} = \tau_\mu \tau_\nu \quad \{y_{i=1,\dots,D}^\mu = e_a^\mu, \bar{y}_i^\mu = 0\} \quad e_a^\mu e_b^\nu \delta^{ab} = h^{\mu\nu}$$

- **SNC can be identified with the (1,1) parametrization**

- **Riemann geometry is identified with (0,0) parametrization**
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(SMALL DETOUR) STRING COUPLED TO DFT BACKGROUND

- For reference it will be convenient to write down the coupling of a string with a DFT background parametrized this way [1707.03713 Morand and Park, 1908.00074 Blair](#)

$$S = \int d^2\sigma \left[-\frac{1}{2} \sqrt{-\gamma} \gamma^{\alpha\beta} K_{\mu\nu} \partial_\alpha X^\mu \partial_\beta X^\nu - \frac{1}{2} \epsilon^{\alpha\beta} B_{\mu\nu} \partial_\alpha X^\mu \partial_\beta X^\nu \right. \\ \left. + \beta_{\alpha i} x_\mu^i (\sqrt{-\gamma} \gamma^{\alpha\beta} - \epsilon^{\alpha\beta}) \partial_\beta X^\mu - \bar{\beta}_{\alpha \bar{i}} \bar{x}_\mu^{\bar{i}} (\sqrt{-\gamma} \gamma^{\alpha\beta} + \epsilon^{\alpha\beta}) \partial_\beta X^\mu \right]$$

Lagrange multiplier

Lagrange multiplier

There will be $n+\bar{n}$ Lagrange multipliers enforcing
Hamiltonian constraints

- This action will correspond to the Polyakov action of a string. On the appropriate parametrization it reduces to the known NR-Polyakov actions for TNC and SNC
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Double Field Theory

Contact with NR
Geometry

**General
Parametrization**

Stands by itself

$$\mathcal{H}_{MN} = \begin{pmatrix} K_{\mu\nu} - \mathcal{B}_{\mu\rho} H^{\rho\sigma} \mathcal{B}_{\sigma\nu} + 2 (Z^T)_{(\mu}^{\rho} \mathcal{B}_{\nu)\rho} & -H^{\nu\rho} \mathcal{B}_{\rho\mu} + Z_{\mu}^{\nu} \\ -H^{\mu\rho} \mathcal{B}_{\rho\nu} + Z_{\mu}^{\nu} & H^{\mu\nu} \end{pmatrix}$$

Doubled Gravity

**NS-NS Non-Riemannian
Supergravity
(h, τ, B, ...)**

$$S_{\text{DFT}} = \int d^D X d^D \tilde{X} e^{-2d} \mathcal{R}$$

$$\begin{aligned} \mathcal{R} = & 4\mathcal{H}^{MN} \partial_M \partial_N d - \partial_M \partial_N \mathcal{H}^{MN} - 4\mathcal{H}^{MN} \partial_M d \partial_N d + 4\partial_M \mathcal{H}^{MN} \partial_N d \\ & + \frac{1}{8} \mathcal{H}^{MN} \partial_M \mathcal{H}^{KL} \partial_N \mathcal{H}_{KL} - \frac{1}{2} \mathcal{H}^{MN} \partial_M \mathcal{H}^{KL} \partial_K \mathcal{H}_{NL} \end{aligned}$$

**TORSIONAL NEWTON
CARTAN GRAVITY**

GENERAL CONSIDERATIONS

- **Recall that there is a transverse metric $h_{\mu\nu}$ and a longitudinal clock one form τ_μ**

$$h^{\mu\rho}h_{\rho\nu} - v^\mu\tau_\nu = \delta_\nu^\mu \quad v^\mu\tau_\mu = -1 \quad h^{\mu\nu}\tau_\nu = h_{\mu\nu}v^\nu = 0$$

$$h_{\mu\nu} = e_\mu^a e_\nu^b \delta_{ab}$$

- **The theory has intrinsic torsion defined via** [2009.01948 Figueroa-O'Farrill](#)

$$F = d\tau$$

- **The theory is locally invariant under Galilean Boosts**

$$\delta e_\mu^a = \lambda^a \tau_\mu$$

- **We can add a U(1) central extension by adding the one form U(1) connection m**

$$\delta m_\mu = \lambda_a e_\mu^a + \partial_\mu \sigma$$

GENERAL CONSIDERATIONS

- It is useful to introduce Galilean boost invariant objects

$$\bar{h}_{\mu\nu} \equiv h_{\mu\nu} - \tau_\mu m_\nu - \tau_\nu m_\mu$$

$$\hat{v}^\mu \equiv v^\mu - h^{\mu\nu} m_\nu$$

Newton's potential $\Phi \equiv -v^\rho m_\rho + \frac{1}{2} h^{\rho\sigma} m_\rho m_\sigma$

- We will assume there is non-vanishing torsion and fix the connection to be compatible with $(\tau_\mu, h^{\mu\nu})$

$$D_\rho h^{\mu\nu} = 0$$

$$D_\rho \tau_\mu = 0$$

$$\tau_\rho \Gamma_{[\mu\nu]}^\rho = \partial_{[\mu} \tau_{\nu]} \equiv F_{\mu\nu}$$

Acceleration $a_\mu \equiv v^\mu F_{\mu\nu}$

EMBEDDING INTO DFT

- **TNC with U(1) extension can be embedded into a relativistic metric with a null isometry**

$$\mathcal{H}_{MN} = \begin{pmatrix} \bar{h}_{\mu\nu} & \tau_\mu & 0 & 0 \\ \tau_\mu & 0 & 0 & 0 \\ 0 & 0 & h^{\mu\nu} & -\hat{v}^\mu \\ 0 & 0 & -\hat{v}^\mu & 2\Phi \end{pmatrix} \xrightarrow{\text{O(D,D) rotation}} \mathcal{H}_{MN} = \begin{pmatrix} \bar{h}_{\mu\nu} & 0 & 0 & \tau_\mu \\ 0 & 2\Phi & -\hat{v}^\nu & 0 \\ 0 & -\hat{v}^\mu & h^{\mu\nu} & 0 \\ \tau_\nu & 0 & 0 & 0 \end{pmatrix}$$

(0,0) parametrization

From here we can read the following

$$K_{mn} = \begin{pmatrix} h_{\mu\nu} & 0 \\ 0 & 0 \end{pmatrix} \quad H^{mn} = \begin{pmatrix} h^{\mu\nu} & 0 \\ 0 & 0 \end{pmatrix} \quad \mathcal{B}_{mn} = \begin{pmatrix} 0 & -m_\mu \\ m_\nu & 0 \end{pmatrix}$$

Both K and H have two null eigenvectors, so we are dealing with a **(1,1) parametrization**

The U(1) central extension is inherited from the 1-form symmetry of the B-field

EMBEDDING INTO DFT (ADDING MATTER)

- **We can add a two form field $\bar{B}_{\mu\nu}$ and a one form field \mathcal{N}_μ , they have the interpretation of the KK-components of the d+1-dimensional relativistic B-field.**

$$K_{mn} = \begin{pmatrix} h_{\mu\nu} & 0 \\ 0 & 0 \end{pmatrix} \quad H^{mn} = \begin{pmatrix} h^{\mu\nu} & h^{\mu\rho}\mathcal{N}_\rho \\ h^{\nu\rho}\mathcal{N}_\rho & h^{\rho\sigma}\mathcal{N}_\rho\mathcal{N}_\sigma \end{pmatrix} \quad \mathcal{B}_{mn} = \begin{pmatrix} \bar{B}_{\mu\nu} & -m_\mu \\ m_\nu & 0 \end{pmatrix}$$

$$x_m = \frac{1}{\sqrt{2}} \begin{pmatrix} \tau_\mu - \mathcal{N}_\mu \\ 1 \end{pmatrix}, \quad \bar{x}_m = \frac{1}{\sqrt{2}} \begin{pmatrix} \tau_\mu + \mathcal{N}_\mu \\ -1 \end{pmatrix},$$
$$y^m = \frac{1}{\sqrt{2}} \begin{pmatrix} -v^\mu \\ 1 - v^\mu\mathcal{N}_\mu \end{pmatrix}, \quad \bar{y}^m = \frac{1}{\sqrt{2}} \begin{pmatrix} -v^\mu \\ -1 - v^\mu\mathcal{N}_\mu \end{pmatrix}.$$

- **There is an additional U(1) symmetry associated to \mathcal{N} , we have chosen $\bar{B}_{\mu\nu}$ such that it is invariant under Galilean boosts but not under this additional U(1) transformation**
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EMBEDDING INTO DFT (ADDING MATTER)

- It is convenient to define the field strengths and the electric field e

$$\begin{aligned} H &\equiv d\bar{B} & e &= \hat{v}^\rho b_{\rho\mu} \\ b &\equiv d\mathcal{N} \end{aligned}$$

- The “standard” dilation can also be added via the identification

$$e^{-2d} = \sqrt{\frac{\det \bar{h}}{2\Phi}} e^{-2\phi}$$



ACTION

- **Using the DFT generalized metric we find the action**

$$S = \int d^d x e \left[\mathcal{R} + \frac{1}{2} a^\mu a_\mu + \frac{1}{2} \mathbf{e}^\mu \mathbf{e}_\mu - 4a^\mu D_\mu \phi + 4D^\mu \phi D_\mu \phi - \frac{1}{12} H^{\mu\nu\rho} H_{\mu\nu\rho} \right. \\ \left. - \frac{1}{2} \hat{v}^\rho H_{\rho\mu\nu} b^{\mu\nu} - \frac{1}{2} (F^{\mu\nu} F_{\mu\nu} + b^{\mu\nu} b_{\mu\nu}) \Phi \right]$$

- **We will obtain the same action from null reducing the NS-NS action**

- **Due to the identity $\tau_\mu \tau_\nu \delta h^{\mu\nu} = 0$ the action will be missing one equation (Newton's law)**
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EQUATIONS OF MOTION AND COMPARISON WITH TNC BETA FUNCTIONS

- **The TNC beta function computation was performed under some assumptions/restrictions**

The twistless constraint was imposed from the onset

$$F_{\mu\nu}F^{\mu\nu} = 0 \leftrightarrow F \wedge \tau = 0$$

U(1) invariance was imposed, rather than derived

- **Using DFT (or directly the null reduction of the NS-NS sector) we can generalize to arbitrary torsion**
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EQUATIONS OF MOTION AND COMPARISON WITH TNC BETA FUNCTIONS

➤ From the $\delta\Phi$ variation the generalization of the twistless constraint shows up

“Raised indices” is short hand notation for contraction with the inverse metric h

$$F_{\mu\nu}F^{\mu\nu} = b_{\mu\nu}b^{\mu\nu}$$

Only the “magnetic piece” of b sources twist

The equivalent of this expressions follows from the beta function associated to the Lagrange multipliers

$$\delta\langle\beta\bar{\beta}\rangle = b_{\mu\nu}b^{\mu\nu} = 0$$

Obtained TNC beta function - twistless torsion was imposed $F_{\mu\nu}F^{\mu\nu} = 0 \leftrightarrow F \wedge \tau = 0$



EQUATIONS OF MOTION AND COMPARISON WITH TNC BETA FUNCTIONS

➤ **From the variation of the matter fields $\{\delta\phi, \delta\mathbf{B}, \delta\mathcal{N}\}$ we find the equations**

$$D_\mu D^\mu \phi + a^\mu D_\mu \phi - 2D_\mu \phi D^\mu \phi = \frac{1}{2} \mathbf{e}^2 - \frac{1}{12} H_{\mu\nu\rho} H^{\mu\nu\rho} - \frac{1}{2} \hat{v}^\lambda H_{\lambda\mu\nu} b^{\mu\nu} - \frac{1}{2} F_{\mu\nu} F^{\mu\nu} \Phi$$

Dilaton equation - Beta function computation involves two loops and has not been done

$$D^\rho H_{\rho\mu\nu} + a^\rho H_{\rho\mu\nu} - 2D^\rho \phi H_{\rho\mu\nu} = 2D_{[\mu} \mathbf{e}_{\nu]} - 2\hat{v}^\lambda D_\lambda b_{\mu\nu} + 2a_{[\mu} \mathbf{e}_{\nu]} + 4b^\rho_{[\mu} F_{\nu]\rho} \Phi \\ + (2\hat{v}^\rho D_\rho \phi - D_\rho \hat{v}^\rho) b_{\mu\nu}$$

Maxwell Equation - Same as the computed TNC beta function for \mathbf{B} (when torsion is twistless)

$$D^\rho b_{\rho\mu} - 2D^\rho \phi b_{\rho\mu} = \frac{1}{2} F^{\rho\sigma} H_{\rho\sigma\mu}$$

Equation for \mathcal{N} - Same as the computed TNC beta function for \mathcal{N} (when torsion is twistless)

EQUATIONS OF MOTION AND COMPARISON WITH TNC BETA FUNCTIONS

- From the variation $\delta\tau$ we find the vector equation

$$D^\rho F_{\rho\mu} + a^\rho F_{\rho\mu} - 2D^\rho \phi F_{\rho\mu} = \frac{1}{2} b^{\rho\sigma} H_{\rho\sigma\mu} + 2 \epsilon^\rho b_{\rho\mu}$$

Equation for τ , when the electric field is zero it matches the TNC beta functions.

Otherwise there seems to be a factor of 2 mismatch

- When torsion has twist we need the factor appearing in the DFT computation to preserve the U(1) mass invariance
- During the TNC beta function computation we are forced to make torsion twistless to keep the computation covariant.
- U(1) invariance was imposed, rather than derived, on the TNC beta function computation. There is the possibility that we missed some terms that are U(1) invariant when torsion is twistless.
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THE MISSING EQUATION

- **The variation of the TNC metrics $\{\delta v, \delta h\}$ and the missing equation (Newton's law) can be combined into the Einstein equation**

$$\mathcal{R}_{(\mu\nu)} + 2D_{(\mu}D_{\nu)}\phi - \frac{1}{4}h^{\rho\sigma}h^{\lambda\kappa}H_{\mu\rho\lambda}H_{\nu\sigma\kappa} = \frac{a_{\mu}a_{\nu} - \epsilon_{\mu}\epsilon_{\nu}}{2} - \hat{v}^{\rho}D_{(\mu}F_{\nu)\rho} + \hat{v}^{\lambda}h^{\rho\sigma}b_{\rho(\mu}H_{\nu)\lambda\sigma} - (F_{\mu\rho}F_{\nu\sigma}h^{\rho\sigma} - b_{\mu\rho}b_{\nu\sigma}h^{\rho\sigma})\Phi$$

Einstein equation - It matches the bar h TNC beta function (twistless limit)

- **The missing equation (Newton's law) can be read directly from the DFT equations of motion but not from a variation of the action**

$$D^{\mu}D_{\mu}\Phi + 3a^{\mu}D_{\mu}\Phi + m_{\Phi}^2\Phi - 2F_{\mu\nu}F^{\mu\nu}\Phi^2 = \rho_{\mathcal{K}} + \rho_m$$

Time-time projection of Einstein equation

Function of extrinsic curvature

Function of torsion and matter

Function of H and dilaton

WHY IS IT MISSING?

- **Relativistic perspective: The null reduction sets $g_{uu}=0$ off-shell so its equation of motion is missing.**
- **Symmetry perspective: Possible emergence of a dilation symmetry (inherited from its SNC embedding).**
- **DFT perspective: This is a known DFT phenomenon due to the fixing of (n, \bar{n}) .**

1909.10711 K. Cho and J-H Park

Analysis of the DFT fluctuations show that $n\bar{n}$ equations change the type of non-Riemannianity. Fixing (n, \bar{n}) removes this equations.

- **We should think of these sectors of DFT as particular solutions rather than independent theories.**
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CARROLL

GENERAL CONSIDERATIONS

- **The metric structure is the same as in TNC (same notation as well)**

$$h^{\mu\rho}h_{\rho\nu} - v^\mu\tau_\nu = \delta_\nu^\mu \quad v^\mu\tau_\mu = -1 \quad h^{\mu\nu}\tau_\nu = h_{\mu\nu}v^\nu = 0$$

$$h_{\mu\nu} = e_\mu^a e_\nu^b \delta_{ab}$$

- **The theory has intrinsic torsion defined through** [2009.01948 Figueroa-O'Farrill](#)

$$\mathcal{K}_{\mu\nu} = -\frac{1}{2}\mathcal{L}_v h_{\mu\nu}$$

- **The theory is locally invariant under Carroll Boosts**

$$\delta_C \tau_\mu = \lambda_\mu, \quad \delta_C h^{\mu\nu} = 2h^{\rho(\mu}v^{\nu)}\lambda_\rho$$

- **A contravariant vector M can be added (in a similar fashion as m was for TNC)**

$$\delta M^\mu = h^{\mu\nu}\lambda_\nu$$

From the nature of the embedding there is no additional symmetry associated to M

GENERAL CONSIDERATIONS

➤ **It is useful to introduce Boost invariant objects**

$$\begin{aligned}\hat{\tau}_\mu &= \tau_\mu - h_{\mu\nu}M^\nu, \\ \hat{h}^{\mu\nu} &= h^{\mu\nu} - 2M^{(\mu}v^{\nu)} + 2\Phi v^\mu v^\nu \equiv \bar{h}^{\mu\nu} + 2\Phi v^\mu v^\nu, \\ \Phi &= -M^\mu \tau_\mu + \frac{1}{2}h_{\mu\nu}M^\mu M^\nu = -M^\mu \hat{\tau}_\mu - \frac{1}{2}h_{\mu\nu}M^\mu M^\nu,\end{aligned}$$

➤ **We will consider a connection satisfying**

$$\begin{aligned}\bar{D}_\mu \hat{h}^{\rho\sigma} &= -4\mathcal{K}_{\mu\lambda} \bar{h}^{\lambda(\rho} v^{\sigma)} \Phi, \\ \bar{D}_\mu \hat{\tau}_\nu &= -2\mathcal{K}_{\mu\nu} \Phi\end{aligned}$$

➤ **The intrinsic torsion of Carroll is associated with the extrinsic curvature instead of F**

EMBEDDING INTO DFT (COMPARISON WITH TNC)

- **Carroll with U(1) extension can be embedded into a relativistic metric with a null isometry**

$$\begin{array}{ccc}
 (\mathcal{H}_{\text{Carroll}})_{MN} = \begin{pmatrix} h_{\mu\nu} & -\hat{\tau}_\mu & 0 & 0 \\ -\hat{\tau}_\mu & 2\Phi & 0 & 0 \\ 0 & 0 & \bar{h}^{\mu\nu} & v^\mu \\ 0 & 0 & v^\mu & 0 \end{pmatrix} & \xrightarrow[\text{We swapped all directions}]{\text{O(D,D) rotation}} & (\mathcal{H}_{\text{Carroll}})_{MN} \rightarrow \begin{pmatrix} \bar{h}^{\mu\nu} & 0 & 0 & v^\mu \\ 0 & 2\Phi & -\hat{\tau}_\nu & 0 \\ 0 & -\hat{\tau}_\mu & h_{\mu\nu} & 0 \\ v^\nu & 0 & 0 & 0 \end{pmatrix} \\
 \updownarrow \text{Comparison with TNC} & & \updownarrow \text{Some identifications can be made between TNC and Carroll} \\
 (\mathcal{H}_{\text{TNC}})_{MN} = \begin{pmatrix} \bar{h}_{\mu\nu} & \tau_\mu & 0 & 0 \\ \tau_\mu & 0 & 0 & 0 \\ 0 & 0 & h^{\mu\nu} & -\hat{v}^\mu \\ 0 & 0 & -\hat{v}^\mu & 2\Phi \end{pmatrix} & \xrightarrow[\text{We only swapped null directions}]{\text{O(D,D) rotation}} & (\mathcal{H}_{\text{TNC}})_{MN} = \begin{pmatrix} \bar{h}_{\mu\nu} & 0 & 0 & \tau_\mu \\ 0 & 2\Phi & -\hat{v}^\nu & 0 \\ 0 & -\hat{v}^\mu & h^{\mu\nu} & 0 \\ \tau_\nu & 0 & 0 & 0 \end{pmatrix}
 \end{array}$$

They are the same when $m=0$ and $M=0$

TNC AND CARROLL IDENTIFICATION

- **By comparing TNC and Carroll generalized metric we can map one to the other after the identification**

$$\begin{aligned}\bar{h}_{(c)}^{\mu\nu} &\leftrightarrow \bar{h}_{\mu\nu}^{(TNC)}, & \hat{\tau}_{\mu}^{(c)} &\leftrightarrow \hat{v}_{(TNC)}^{\mu}, & \Phi^{(c)} &\leftrightarrow \Phi^{(TNC)}, \\ h_{\mu\nu}^{(c)} &\leftrightarrow h_{(TNC)}^{\mu\nu}, & v_{(c)}^{\mu} &\leftrightarrow \tau_{\mu}^{(TNC)}, & M_{(c)}^{\mu} &\leftrightarrow m_{\mu}^{(TNC)}\end{aligned}$$

This identification has been made before in 1505.05011

- **DFT makes this evident and seems to imply Carroll and TNC might be related through a T-duality transformation, equivalent to a $c \rightarrow 1/c$ rule.**
 - **We have not explored this further**
-

CARROLL ACTION AND EQUATIONS OF MOTION

➤ **The action for Carroll is given by**

$$S = \int d^d x e \left[\bar{\mathcal{R}} + \frac{1}{2} a^\mu a_\mu + \frac{1}{2} \mathbf{e}^\mu \mathbf{e}_\mu - 4a^\mu \bar{D}_\mu \phi + 4\bar{D}^\mu \phi \bar{D}_\mu \phi + 4v^\mu v^\nu \bar{D}_\mu \phi \bar{D}_\nu \Phi \right. \\ \left. - 8\Phi \mathcal{K} v^\rho \bar{D}_\rho \phi - \frac{1}{12} H_{\mu\nu\rho} H^{\mu\nu\rho} + \frac{1}{2} b^{\mu\nu} v^\rho H_{\mu\nu\rho} \right]$$

➤ **There is also a missing equation, the corresponding Newton's law is**

$$\bar{D}^\mu \bar{D}_\nu \Phi - a^\mu \bar{D}_\mu \Phi - 2\bar{D}^\mu \phi \bar{D}_\mu \Phi = \frac{1}{4} (F^{\mu\nu} F_{\mu\nu} - b^{\mu\nu} b_{\mu\nu})$$

➤ **There are no constraints on F, the equivalent Carroll torsion constraints will be constraints on the extrinsic curvature that follow from the $\delta\Phi$ variation**

QUICK GLANCE AT THE EQUATIONS OF MOTION

➤ Torsion constraints

$$\bar{\mathcal{R}}_{\mu\nu}v^\mu v^\nu = \frac{1}{4}v^\rho v^\sigma H^{\mu\nu}{}_\rho H_{\mu\nu\sigma} - 2v^\mu v^\nu \bar{D}_\mu \bar{D}_\nu \phi$$

➤ Equations for τ , and Einstein equation

$$\begin{aligned} \bar{D}^\rho F_{\rho\mu} + a^\rho F_{\rho\mu} - 2\bar{D}^\rho \phi F_{\rho\mu} &= \frac{1}{2}b^{\rho\sigma} H_{\rho\sigma\mu} + \epsilon^\rho b_{\mu\rho} + 2\bar{D}^\rho \mathcal{K}_{\rho\mu} - 2\mathcal{K}\bar{D}_\mu \Phi \\ &+ 2v^\rho \bar{D}_\mu \bar{D}_\rho \Phi - 4v^\rho \bar{D}_\rho \phi D_\mu \Phi \\ \bar{\mathcal{R}}_{(\mu\nu)} + 2\bar{D}_{(\mu} \bar{D}_{\nu)} \phi - \frac{1}{4}H_\mu{}^{\rho\sigma} H_{\nu\rho\sigma} &= \frac{a_\mu a_\nu - \epsilon_\mu \epsilon_\nu}{2} + D_{(\mu} a_{\nu)} - F_{(\mu}{}^\rho \mathcal{K}_{\nu)\rho} + v^\rho b_{(\mu}{}^\sigma H_{\nu)\rho\sigma} \\ &+ 4\Phi v^\rho \left(\bar{D}_\rho \mathcal{K}_{\mu\nu} - \mathcal{K} \mathcal{K}_{\mu\nu} + \frac{\bar{D}_\rho \Phi}{\Phi} \mathcal{K}_{\mu\nu} \right) \end{aligned}$$

QUICK GLANCE AT THE EQUATIONS OF MOTION

➤ Equations for the matter fields

$$\bar{D}_\mu \bar{D}^\mu \phi + a^\mu \bar{D}_\mu \phi - 2\bar{D}_\mu \phi \bar{D}^\mu \phi = 2v^\mu v^\nu D_\mu \Phi D_\nu \phi - \frac{1}{2} H^{\rho\mu\nu} H_{\rho\mu\nu} + \frac{1}{2} \mathbf{e}^\mu \mathbf{e}_\mu + \frac{1}{2} v^\rho b^{\mu\nu} H_{\rho\mu\nu}$$

$$\bar{D}^\rho b_{\rho\mu} - 2\bar{D}^\rho \phi b_{\rho\mu} = \frac{1}{2} F^{\rho\sigma} H_{\rho\sigma\mu} + 2v^\rho \bar{D}^\sigma \Phi H_{\rho\sigma\mu}$$

$$\bar{D}^\rho H_{\rho\mu\nu} + a^\rho H_{\rho\mu\nu} - 2\bar{D}^\rho \phi H_{\rho\mu\nu} = 2b_{[\mu}{}^\rho \mathcal{K}_{\nu]\rho} - \mathcal{K} b_{\mu\nu} + v^\rho (\bar{D}_\rho b_{\mu\nu} - 2\bar{D}_\rho \phi b_{\mu\nu} + 2v^\sigma \bar{D}_\sigma \Phi H_{\rho\mu\nu})$$



STRING NEWTON CARTAN

GENERAL CONSIDERATIONS

- **Recall that there are two longitudinal directions with a Lorentz structure**

$$h^{\mu\rho}h_{\rho\nu}^{\perp} - v_A^{\mu}\tau_{\nu}^A = \delta_{\nu}^{\mu}, \quad v_A^{\mu}\tau_{\mu}^B = -\delta_A^B, \quad \tau_{\mu}^A h^{\mu\rho} = v_A^{\mu}h_{\mu\rho}^{\perp} = 0$$

$$h_{\mu\nu} = E_{\mu}^{A'}E_{\nu}^{B'}\delta_{A'B'}$$

Indices are raised with
Minkowski metric

- **We can define torsion as**

$$F_{\mu\nu}^A \equiv 2\partial_{[\mu}\tau_{\nu]}^A + 2\epsilon^A_B\omega_{[\mu}\tau_{\nu]}^B = 2\nabla_{[\mu}\tau_{\nu]}^A$$

- **Galilean boosts become String Galilean boosts**

$$\delta_{\Sigma}v_A^{\mu} = -E_{A'}^{\mu}\Sigma_{A'}^{A'}, \quad \delta_{\Sigma}E_{\mu}^{A'} = -\tau_{\mu}^A\Sigma_{A'}^{A'}, \quad \delta E_{A'}^{\mu} = \delta_{\Sigma}\tau_{\mu}^A = 0$$

- **A U(1) mass symmetry, called the Z_A symmetry, is usually included by the addition of a gauge field m**

$$\delta_Z m_{\mu}^A = D_{\mu}\sigma^A$$

$$\delta_{\Sigma} m_{\mu}^A = E_{\mu}^{A'}\Sigma_{A'}^A$$

LET'S TALK ABOUT Z_A

- For a classical SNC theory (string in SNC background) to have arbitrary torsion and preserve Z_A invariance we need a B-field that transforms as [1907.01663 Harmark et al.](#)

$$\delta B_{\mu\nu} = 2\epsilon_{AB}\tau_{[\mu}^A D_{\nu]}\sigma^B$$

- We can use m to write down Boost invariant (but no Z_A invariant) fields

$$\begin{aligned}\bar{h}_{\mu\nu} &= h_{\mu\nu}^\perp + 2\eta_{AB}m_{(\mu}^A \tau_{\nu)}^B, \\ u_A^\mu &= v_A^\mu + h^{\mu\rho}m_{\rho A}, \\ \Phi^{AB} &= 2u^{\rho(A}m_{\rho}^{B)} - h^{\mu\nu}m_\mu^A m_\nu^B = -u^{\mu A}u^{\nu B}\bar{h}_{\mu\nu},\end{aligned}$$

- The Z_A symmetry is part of a larger Stueckelberg symmetry

This shift symmetry is related to the DFT generalized shift symmetry

$$\delta\bar{h}_{\mu\nu} = 2\tau_{(\mu}^A D_{\nu)}\sigma_A, \quad \delta B_{\mu\nu} = 2\epsilon_{AB}\tau_{[\mu}^A D_{\nu]}\sigma^B,$$

- m can be gauge away but B will not longer be Boost invariant This choice has been used in [2102.06974](#) were they derived SNC equations from a $1/c$ expansion
-

DFT EMBEDDING

- We got the DFT embedding by matching the SNC Polyakov and DFT Polyakov actions

$$\mathcal{H}_{AB} = \begin{pmatrix} 1 & \mathcal{B} \\ 0 & 1 \end{pmatrix} \begin{pmatrix} K & Z \\ Z^T & H \end{pmatrix} \begin{pmatrix} 1 & 0 \\ -\mathcal{B} & 1 \end{pmatrix}$$

$$K_{\mu\nu} = \bar{h}_{\mu\nu} + \Phi_{AB} \tau_{\mu}^A \tau_{\nu}^B,$$

$$H^{\mu\nu} = h^{\mu\nu},$$

$$Z_{\nu}^{\mu} = -\epsilon_{AB} u^{\mu A} \tau_{\nu}^B,$$

$$\mathcal{B}_{\mu\nu} = B_{\mu\nu} - \frac{1}{2} \Phi \epsilon_{AB} \tau_{\mu}^A \tau_{\nu}^B,$$

- We can reduce SNC to TNC by comparing the generalized metrics and assuming an isometry along a longitudinal compact direction [1907.01663 Harmark et al.](#)

$$v_1^{\mu} = 0,$$

$$v_0^{\mu} = v^{\mu},$$

$$h_{(SNC)}^{\mu\nu} = h_{(TNC)}^{\mu\nu},$$

$$h_{(SNC)}^{uu} = h^{\rho\sigma} \mathfrak{N}_{\rho} \mathfrak{N}_{\sigma},$$

$$B_{\mu u}^{(SNC)} = -m_{\mu}.$$

$$m_M^A = 0,$$

$$\tau_{\nu}^0 = 0,$$

$$v_1^u = 1,$$

$$v_0^u = v^{\mu} \mathfrak{N}_{\mu},$$

$$h_{(SNC)}^{\mu u} = h^{\mu\rho} \mathfrak{N}_{\rho},$$

$$B_{\mu\nu}^{(SNC)} = B_{\mu\nu}^{(TNC)}$$

$$\tau_u^1 = 1,$$

$$E_u^{A'} = 0$$

ACTION AND EQUATIONS OF MOTION

➤ The SNC action is found to be

Acceleration, defined by the contraction of F and u

$$S = \int d^D x e \left[\mathcal{R} - a^{\mu AB} \left(a_{\mu(AB)} - \frac{1}{2} \eta_{AB} a_{\mu} \right) + (a^{\mu} - 2D^{\mu} \phi) (a_{\mu} - 2D_{\mu} \phi) \right. \\ \left. - \frac{1}{2} F^{\mu\nu A} F_{\mu\nu}^B \left(\Phi_{AB} - \frac{1}{2} \eta_{AB} \Phi \right) + \frac{1}{2} \epsilon_{AB} u^{\rho A} F^{\mu\nu B} H_{\rho\mu\nu} - \frac{1}{12} H^{\rho\mu\nu} H_{\rho\mu\nu} \right]$$

➤ There is also a missing equation

Spatial piece of acceleration

$$u^{\mu A} u^{\nu}_A \mathcal{R}_{\mu\nu} + 2u^{\mu A} u^{\nu}_A D_{\mu} D_{\nu} \phi - \frac{1}{4} u^{\mu A} u^{\nu}_A H_{\mu\rho\sigma} H_{\nu}^{\rho\sigma} = \frac{3}{2} \mathcal{S}^{\rho AB} D_{\rho} \Phi_{AB} - \frac{3}{4} a^{\mu} D_{\mu} \Phi \\ - \frac{3}{4} a^{\mu} a_{\mu} \Phi + \mathcal{S}^{\mu AB} \mathcal{S}_{\mu AC} \Phi_B^C - 2f^A f_A + \epsilon^{AB} Q_{AB}$$

Totally antisymmetric longitudinal piece of torsion

➤ It agrees with the SNC beta functions computed at zero torsion (foliation constraint)

QUICK GLANCE AT THE EQUATIONS OF MOTION

➤ Torsion constraint

$$F^{\mu\nu A} F_{\mu\nu A} = 0$$

➤ We could not combine the u equation into a single expression, we only found its projections

$$D^\rho F^\mu_{\rho A} + a_{\rho A}^B F^{\mu\rho}_B - 2F^\mu_{\rho A} D^\rho \phi = \frac{1}{2} \epsilon_{AB} F^{\rho\sigma B} H^\mu_{\rho\sigma}$$

$$D^\rho \mathcal{S}_\rho^{AB} + a^\rho \mathcal{S}_\rho^{AB} - 2\mathcal{S}^{\rho AB} D_\rho \phi = -\frac{1}{4} F^{\mu\nu A} F_{\mu\nu}^B \Phi + 2\epsilon^{(A}_C \mathcal{F}^{B)C}$$



QUICK GLANCE AT THE EQUATIONS OF MOTION

➤ The same happened for Einstein equations

$$\mathcal{R}^{(\mu\nu)} + 2D^{(\mu}D^{\nu)}\phi - \frac{1}{4}H^\mu_{\rho\sigma}H^{\nu\rho\sigma} = u^\rho_A D^{(\mu}F_\rho^{\nu)A} + \mathcal{S}^{\mu AB}\mathcal{S}^\nu_{AB} \\ - \epsilon^{AB}u^\sigma_A F^{\rho(\mu}H^{\nu)}_{\rho\sigma} - \frac{1}{2}F^{\mu\rho A}F^\nu_{\rho A}\Phi$$

$$h^{\mu\rho}u^\sigma_A \mathcal{R}_{(\rho\sigma)} + 2u^{\rho A}D^\mu D_\rho\phi + a^\mu u^{\rho A}D_\rho\phi - \frac{1}{4}H^\mu_{\rho\sigma}H^\lambda{}^{\rho\sigma}u^{\lambda A} = \frac{1}{2}u^{\rho A}u^\sigma_B D_\rho F_\sigma{}^{\mu B} - u^\rho_B D^\mu a_\rho{}^{(AB)} + u^{\rho A}D^\mu a_\rho \\ - \frac{1}{2}u^{\rho B}D_\rho a^\mu_{BA} + \frac{1}{2}u^{\rho A}D_\rho a^\mu - 2a^{\mu[AB]}u^\rho_B D_\rho\phi - a^\mu u^{\rho A}D_\rho\phi - \frac{1}{2}a^\mu \mathcal{K}^A + \frac{1}{2}a^{\mu BA}\mathcal{K}_B \\ - F^\mu_{\rho C}a^{\rho B(A}\Phi_B^{C)} + a^\rho F^\mu_{\rho C}\Phi^{AC} + \frac{1}{2}a^\rho F_\rho{}^{\mu A}\Phi + \frac{1}{2}F^{\mu\rho B}D_\rho\Phi^A_B - \frac{1}{2}F^{\mu\rho A}D_\rho\Phi \\ + \epsilon^{AB}\mathcal{P}^\mu_B$$

QUICK GLANCE AT THE EQUATIONS OF MOTION

➤ **The matter equations look slightly nicer**

$$D^\rho H_\rho{}^{\mu\nu} + a^\rho H_\rho{}^{\mu\nu} - 2D^\rho\phi H_\rho{}^{\mu\nu} = 2\Omega^{\mu\nu} + \epsilon_{AB}\mathcal{H}^{\mu\nu AB}$$

$$D^\mu D_\mu\phi - \frac{1}{2}D^\mu a_\mu + 2a_\mu D^\mu\phi - 2D^\mu\phi D_\mu\phi - \frac{1}{2}a_\mu a^\mu = \frac{1}{4}\epsilon_{AB}u^{\rho A}F^{\mu\nu B}H_{\rho\mu\nu} - \frac{1}{12}H^{\rho\mu\nu}H_{\rho\mu\nu}$$



COMPARISON WITH 1/C EXPANSION OF NS-NS GRAVITY

2102.06974 Bergshoeff et al.

- **The actions match after imposing the $m=0$ gauge**
- **The missing equation is explained by an emergent dilatation symmetry**

$$\delta\tau_{\mu}^A = \lambda_D \tau_{\mu}^A \quad \delta\phi = \lambda_D \quad \delta\Phi^{AB} = -2\lambda_D \Phi^{AB}$$

- **This symmetry is, of course, present in the action we computed**
-

CONCLUSIONS/SUMMARY

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- **DFT unifies many Non-Riemannian geometries into a single framework**
 - **We used this framework to write down gravitational equations for various non-Riemannian geometries**
 - **Some interesting relations between non-Riemannian geometries can be infer (Carroll and TNC/ TNC and SNC)**
 - **We can try to push this further into understand non-Riemannian notions of “Entropy” or thermal states**

1608.04734 A. Arvanitakis and C. Blair

We only have to understand it once

FUTURE DIRECTIONS

- **Repeat an analogous computation to the Exceptional Field Theory case**
- **ExFT unifies not only 10d supergravity but also 11d M-theory, and has been shown to admit Non-Riemannian parametrizations** [1902.01867 Berman et. al.](#)
- **We are pushing to write 11d Non-Riemannian actions as well as writing other supergravity sectors** [Work in progress with Natale, Chris, and Umut](#)