An Effective Collision Operator for Heat-Flux-Generated Whistler Turbulence

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Microphysics Affects Large-Scale Structure of the ICM



Piffaretti et al. 2005

Plasma is

- high- β
- magnetized $(
 ho_i/L_T \ll 1)$

weakly collisional

- 1. Pressure-Anisotropy-Driven Mirror and Fire Hose Instabilities $(k\rho_i \sim 1)$
 - Reduced viscosity (Kunz et al. 2014)
 - Collisionless sound wave propagation (Kunz et al. 2020)
- 2. Heat-Flux-Driven Whistler Instability $(k
 ho_e\sim 1)$
 - Affects large-scale instabilities (MTI, HBI)

Simulation Results



We use the Fokker-Planck method:

$$\frac{\partial f(t, \mathbf{x}, \mathbf{v})}{\partial t} = -\frac{\partial}{\partial \mathbf{v}} \cdot \mathbf{A}(t, \mathbf{x}, \mathbf{v}) f(t, \mathbf{x}, \mathbf{v}) + \frac{\partial^2}{\partial \mathbf{v} \partial \mathbf{v}} : \mathbf{B}(t, \mathbf{x}, \mathbf{v}) f(t, \mathbf{x}, \mathbf{v})$$
$$\mathbf{A}(t, \mathbf{x}, \mathbf{v}) \doteq \lim_{\Delta t \to "0"} \frac{\langle \Delta \mathbf{v}(t, \mathbf{x}, \mathbf{v}, \Delta t) \rangle}{\Delta t}$$
$$\mathbf{B}(t, \mathbf{x}, \mathbf{v}) \doteq \frac{1}{2} \lim_{\Delta t \to "0"} \frac{\langle \Delta \mathbf{v}(t, \mathbf{x}, \mathbf{v}, \Delta t) \Delta \mathbf{v}(t, \mathbf{x}, \mathbf{v}, \Delta t) \rangle}{\Delta t}$$

where

$$\begin{split} \Delta \boldsymbol{v}(t, \boldsymbol{x}, \boldsymbol{v}, \Delta t) &= \boldsymbol{v}(t + \Delta t, \boldsymbol{x}) - \boldsymbol{v}(t, \boldsymbol{x}) \\ \langle \dots \rangle &\doteq \int \mathrm{d} \boldsymbol{v} (\ \dots) f(t, \boldsymbol{x}, \boldsymbol{v}). \\ \hline \tau_{\mathsf{ac}} \ll \Delta t \ll \nu^{-1} \end{split}$$

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Take $\Delta t \Omega_e = 10$:

1. Parameter ordering is good:

$$au_{\sf ac} \Omega_e \sim 1 \ll \Delta t \Omega_e \sim 10 \ll
u^{-1} \Omega_e \sim 10^3$$

2. $\langle \Delta v^{(1,2)} \rangle$ scales as expected in Δt



$$\begin{aligned} A(v,\xi) &= -\nu_{v}(\xi,\beta_{e},L_{T})(v-v_{\text{th},e0}) \\ B(v,\xi) &= \frac{D_{v}(\xi,\beta_{e},L_{T})}{2}v \\ \nu_{v}(\xi,\beta_{e},L_{T}) &= \nu_{v,0}\beta_{e}^{.63}f_{\nu_{v}}(\xi) \\ D_{v}(\xi,\beta_{e},L_{T}) &= \sigma_{v,0}^{2}\beta_{e}^{.52}f_{D_{v}}(\xi) \end{aligned}$$

 $f_{
u_{
m v}}(\xi)$ and $f_{\sigma_{
m v}}(\xi)$ are nontrivial functions of $\delta B/B_0$

Does not explain $\nu_{w} \sim \beta_{e} v_{\text{th},e} / L_{T}$

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Pitch-angle scattering dominates velocity collision rate

1. Parameter ordering not so good:

$$au_{\sf ac} \Omega_e \sim 1 \leq
u^{-1} \Omega_e \sim 1 - 50$$

2. $\langle \Delta \xi^{(1,2)} \rangle$ does not scales as expected in Δt for $\nu \Delta t \ll 1$

If we naïvely consider this a Fokker-Planck operator:



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Conclusions

- 1. We expanded on and confirmed the scaling of previous numerical studies
- 2. Fokker-Planck method is successful in Δv , but not $\Delta \xi$
 - ▶ We lack sufficient scale separation $(au_{\sf ac} \sim
 u^{-1})$
 - There is some non-diffusive physics we don't understand
- 3. Be careful grabbing a "collision frequency" from PIC simulations
- 4. Shout out to twiddle math

Future Work:

- There is an ion heat flux version of the whistler instability
- ▶ We are currently investigating this using Pegasus++ hybrid-kinetic code

Scale separation should be much higher