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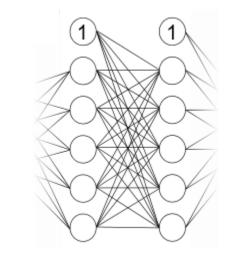
**Uncertainty estimation in** 

magnetic field inference

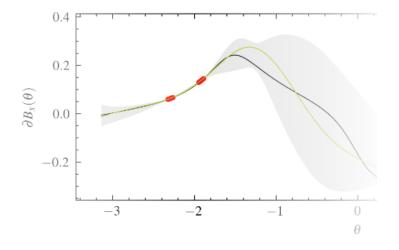


#### **Broader perspective**

Physics



Machine Learning



Uncertainty



## **Physics**

- Magnetic fields from steady currents / permanent magnets
- Magnetic scalar potential

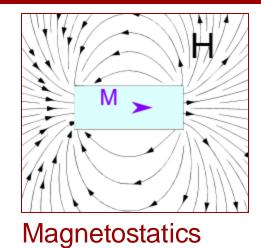
$$\nabla^2 \psi_M = \nabla \cdot \mathbf{M}$$

• Laplace's equation (when M=0, i.e., outside of magnetic material)

$$abla^2\psi_M=~0$$

**Technical University of Denmark** 

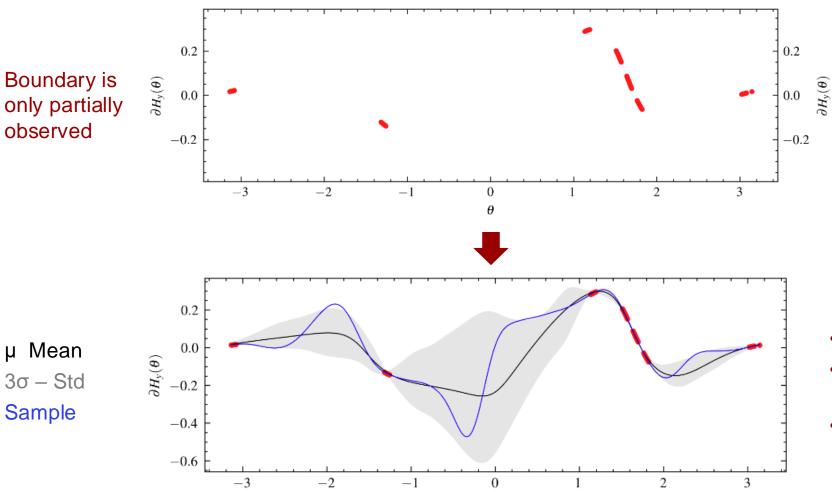
• Solution on circular boundary in 2-D  
Radial coordinate r  
Angular coordinate 
$$\theta$$
  
 $\psi_M(r,\theta) = \frac{a_0}{2} + \sum_{n=1}^{\infty} (a_n \cos n\theta + b_n \sin n\theta) r^n$   
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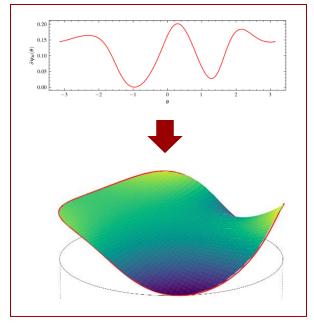


Unique solution to Laplace equation given a Dirichlet boundary condition





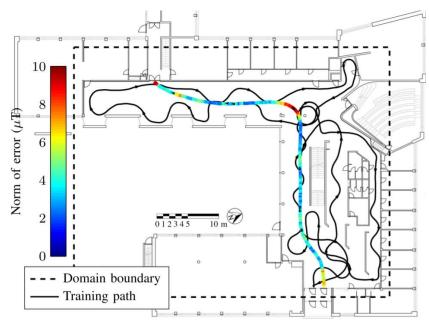
θ



- How does the underlying  $oldsymbol{\psi}$  look like?
- How certain are we about predictions from our model in specific regions?
- How to incorporate measurements, which are obtained in form of **H**?



## **Motivation**

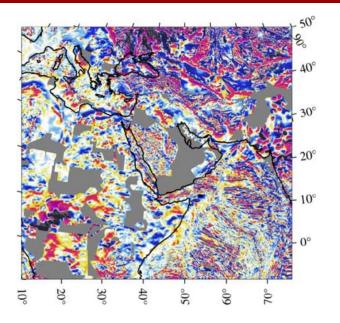


Localization in Robotics [1]

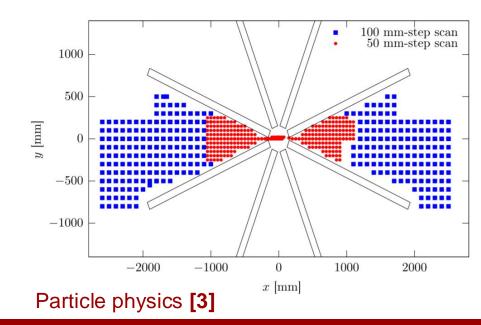
[1] A. Solin et al., IEEE Trans. Robot., vol. 34, no. 4, pp. 1112-1127, Sept. 2018.

[2] S. Maus et al., Geochem. Geophys. Geosys.,vol. 10, no. 8, Aug. 2009.

[3] J.C. Bernauer et al., Nucl. Instrum. Methods Phys. Res. A: Accel. Spectrom. Detect. Assoc. Equip., vol. 823, pp. 9-14, Jul. 2016.



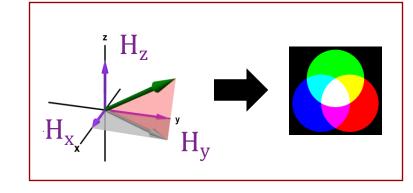
#### Geophysics [2]





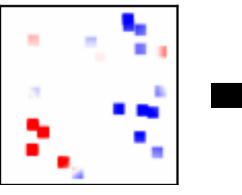
## **Previous work**

#### Magnetic field represented as an image

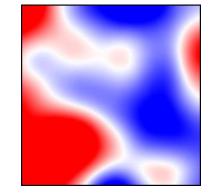


#### Physics-informed Generative Adversarial Networks [4]





Available magnetic field measurements



Prediction from neural network

#### Limitations:

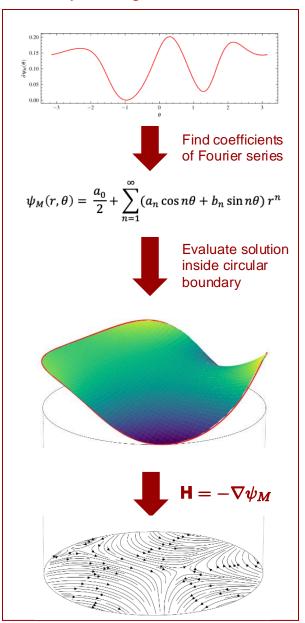
- Same input leads to identical prediction
- No built-in uncertainties
- Embedding physics only as a soft constraint (via loss function)

[4] Pollok, Stefan, et al., Journal of Magnetism and Magnetic Materials 571 (2023): 170556.



**Our new approaches** 0.2 0.2  $\partial H_y(\theta)$  $\partial H_y(\theta)$ . 0.0 0.0 -0.2-0.2-3 -22 3  $^{-1}$ 0 θ **Physics-informed Gaussian Process** Regression neural networks Exponential Sine Squared kernel  $\psi_M$  $2\sin^2\left(\frac{\pi}{p}|\theta-\theta'|\right)$  $L_{pde} = \nabla^2 \psi_M$  $L_{obs} = \| -\nabla \psi_M - H_{obs} \|^2$  $k(\theta, \theta') = \exp$ 

From magnetic scalar potential boundary to magnetic field



21 August 2024 Technical University of Denmark



## **Machine Learning - PINNs**

Architecture

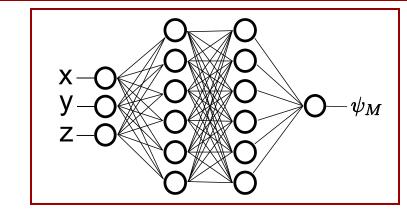
Simple fully-connected neural network

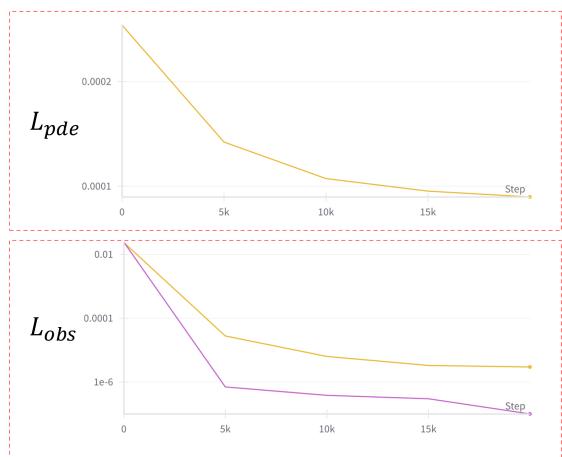
- Automatic differentiation Losses and H can easily be derived
- Collocation points
   Randomly placed across domain as input
- Loss functions

 $L_{pde} = \nabla^2 \psi_M$  $L_{obs} = \| -\nabla \psi_M - H_{obs} \|^2$ 

By construction Limitation to circular boundary  $L_{pde,Fourier} = \nabla^2 \psi_M(r,\theta) = 0$ 

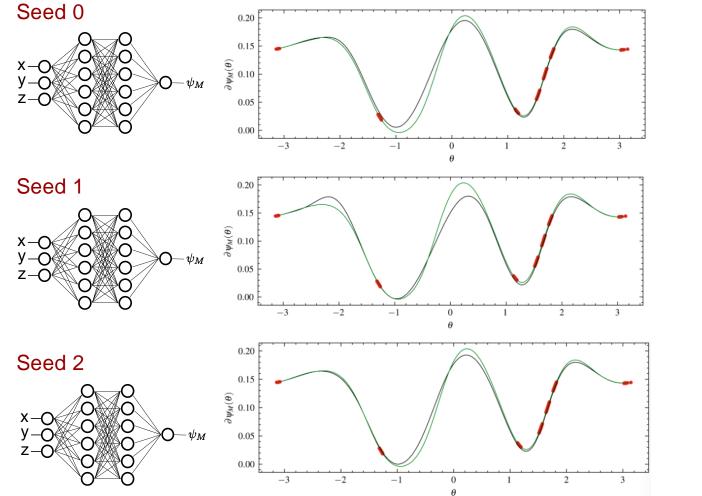
 $L_{obs,Fourier} = \| - \nabla \psi_M(r,\theta) - H_{obs} \|^2$ 



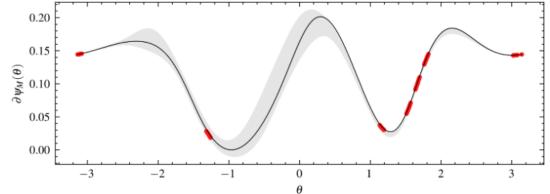




#### **Uncertainty estimation – PINN ensemble**



Mean and variance from an ensemble of 10 PINNs





## **Uncertainty estimation – HMC with PINNs**

#### Bayesian neural networks

Specifying distribution over  $\phi$  and the prediction

Alternative to

random walk

"Predictive distribution as an infinite ensemble of networks" [5] Bayesian statistics over the parameters  $\phi$  of the PINNs based on observations  $\mathcal{D}$ 

$$P(\phi | \mathcal{D}) = \frac{P(\mathcal{D} | \phi) P(\phi)}{P(\mathcal{D})} \cong P(\mathcal{D} | \phi) P(\phi)$$
  
Posterior Likelihood Prior

$$\log P(\mathcal{D} | \phi) \cong -0.5 \times 10^6 \parallel \psi_M - \psi_{M,obs} \parallel^2$$
$$\log P(\phi) = -(0.5\phi^2 + 0.5k \cdot \log 2\pi)$$

#### Monte Carlo integration

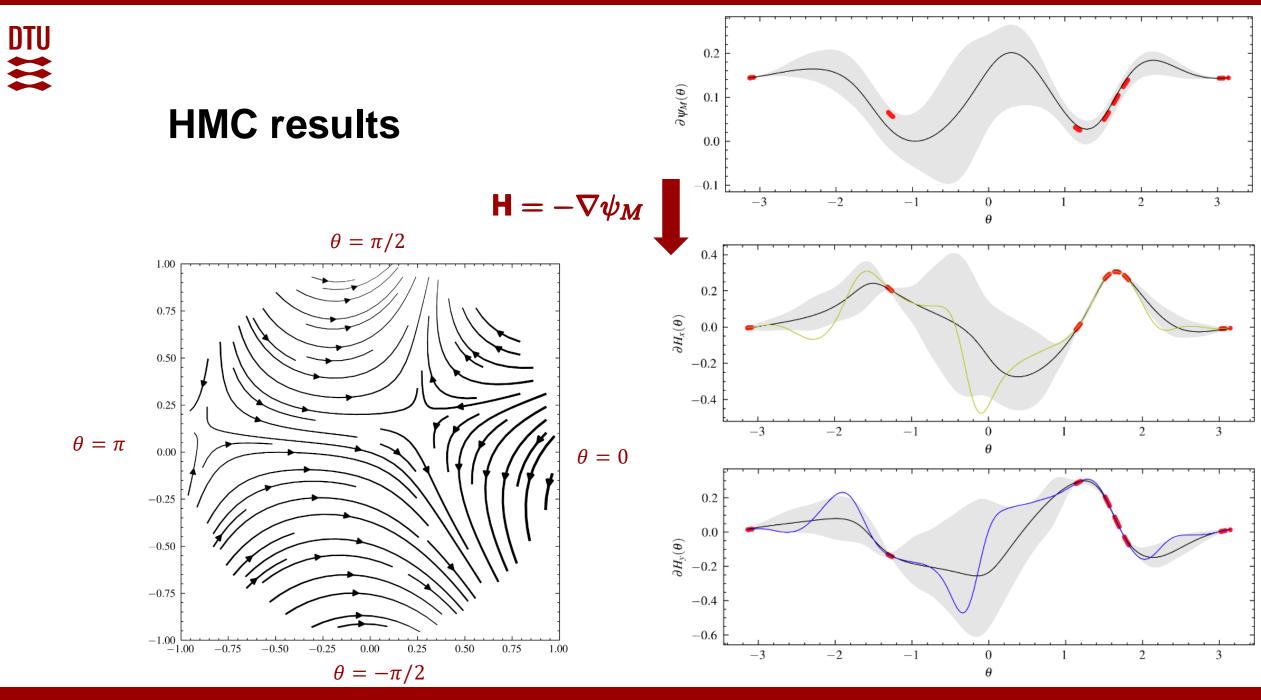
Usage of a finite set of random samples of  $\phi$  to approximate the posterior Naive setup needs a huge number of samples due to the large dimensionality of  $\phi$ 

Markov chain with Hamiltonian dynamics
 Accept a new set φ\* with probability α
 α = min[1, exp(-H(φ\*, p\*) + H(φ, p))]

 $\frac{dq_i}{dt} = \frac{\partial H}{\partial p_i}$  $\frac{dp_i}{dt} = -\frac{\partial H}{\partial q_i}$ H(q, p) = U(q) + K(p)

Negative log-probability as potential energy

[5] Blundell, Charles, et al., International conference on machine learning. PMLR, 2015.





#### **Future work**

- Extension to 3-D with spherical harmonics (sphere as boundary)
- Arbitrary boundaries
- "physics-informed" Gaussian Processes
  - → kernel / covariance matrix respects Gauss' law and Ampère's law

#### **Achievements**

- statistical solution to Laplace's equation from incomplete boundary
   Juseful for many problems in physics
- Improved decision-making
  - → where to measure next with limited amount of resources
  - → how trustworthy is the prediction



## Collaborators

• Department of Energy Conversion and Storage, DTU



Berian



Rasmus

• Department of Applied Mathematics and Computer Science, DTU



Ignacio



Kristoffer



Jes



# **Questions / Collaborations**

Contact spol@dtu.dk www.linkedin.com/stefanpollok





Appendix



## **Machine Learning – Gaussian Process Regression**

• Probability distribution over possible functions

