

Invariant Mass Distributions of SUSY Cascade Decays

Anders Kvellestad

University of Oslo

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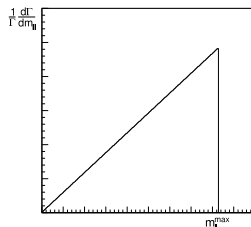
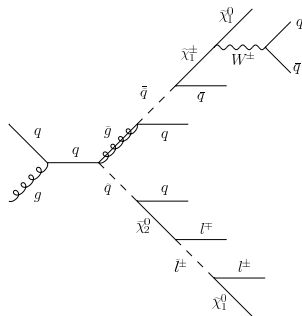
- 1 SUSY Cascades and Mass Measurements
- 2 Results
- 3 Conclusions and Outlook

- 1 SUSY Cascades and Mass Measurements
 - Masses From Kinematic Endpoints
 - Complications
 - The Need for Analytical Shape Formulas
 - Aim and Assumptions
- 2 Results
- 3 Conclusions and Outlook

Masses From Kinematic Endpoints

- If SUSY is discovered, theory parameters must be determined
- Assume conserved R-parity
 - cascade decays
 - $\tilde{\chi}_1^0$ LSP escapes detection
 - inv. mass peaks not accessible
- Endpoints of inv. mass distributions can provide sparticle mass relations
- E.g. ‘dilepton cascade’:
 - 4 masses: $m_{\tilde{q}}$, $m_{\tilde{\chi}_2^0}$, $m_{\tilde{l}}$, $m_{\tilde{\chi}_1^0}$
 - 4 endpoints: m_{ll} , m_{qln} , m_{qlf} , m_{qll}

$$m_{ll}^{\max} = \sqrt{\frac{(m_{\tilde{\chi}_2^0}^2 - m_{\tilde{l}}^2)(m_{\tilde{l}}^2 - m_{\tilde{\chi}_1^0}^2)}{m_{\tilde{q}}^2}}$$



Complications

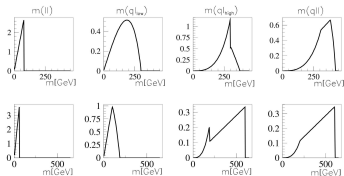
A few complicating aspects:

- Experimental ‘near’/‘far’ ambiguity
 - must replace m_{ql_n}, m_{ql_f} by

$$m_{\text{high}} \equiv \max\{m_{ql_n}, m_{ql_f}\}$$

$$m_{\text{low}} \equiv \min\{m_{ql_n}, m_{ql_f}\}$$

- Shapes vary with sparticle masses
 - danger of ‘feet’ or ‘drops’
- Multiple solutions
- Endpoints depend on mass *differences*
 - strong correlation in results
- Experimental limitations:
 - combinatorics, statistics, backgrounds



[Gjelsten, Miller, Osland, hep-ph/0511008]

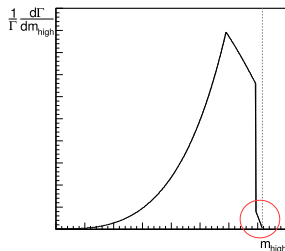
The Need for Analytical Shape Formulas

Analytical expressions might help:

- Shape formulas of the form

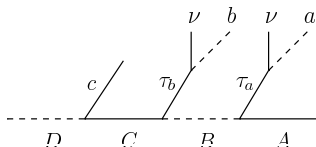
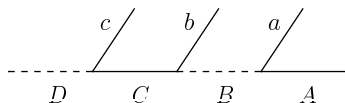
$$\frac{1}{\Gamma} \frac{d\Gamma}{dm} = f(m; \text{particle masses})$$

- Provides correct ‘signal hypothesis’ for endpoint fitting
- Predicts ‘feet’ and ‘drops’ for given mass sets
- Fits of *complete* distributions provide masses directly
 - may lift degeneracies
- Mass correlations still a problem
- Can be used to measure mixing parameters



Aim and Assumptions

- Shape formulas for the ‘dilepton topology’ have been derived ($l = e, \mu$)
[Miller, Osland, Raklev], [Lester]
- **Aim:** Derive shape formulas for the ‘ditau topology’
- More complicated topology due to in-detector τ decays
 - spin effects important
- Simplifying assumptions:
 - $m_a = m_b = m_c = 0$
 - massive particles on-shell



Outline

1 SUSY Cascades and Mass Measurements

2 Results

- The m_{ab} Distribution
- The m_{high} Distribution

3 Conclusions and Outlook

The m_{ab} Distribution

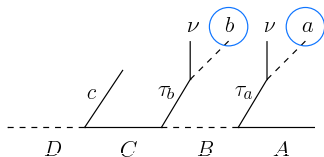
- The m_{ab} distribution

$$\frac{1}{\Gamma} \frac{d\Gamma}{dm_{ab}}$$

- Assume a, b are scalars (pions)

- Helicity states of τ_a, τ_b affect energies of a, b

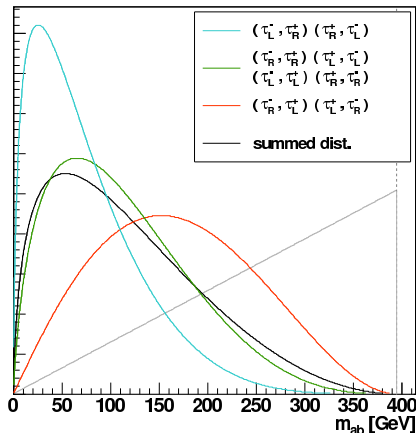
- if τ_b is τ_R^- or τ_L^+ \Rightarrow large E_b
- if τ_b is τ_L^- or τ_R^+ \Rightarrow small E_b



The m_{ab} Distribution

m_C	m_B	m_A
800	600	400

- Weighted towards low m_{ab} values due to escaping ν
- Shapes depend strongly on handedness – endpoints are unaffected
- Shapes are fixed as long as m_τ is negligible
- summed dist. = spin-0 dist.
- Spin shapes for $m_\tau = 0$ derived by Nattermann et al. (2009)



The m_{high} Distribution - No Spin

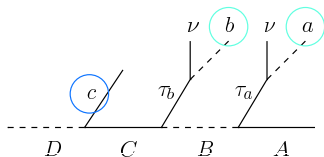
- The m_{high} distribution

$$\frac{1}{\Gamma} \frac{d\Gamma}{dm_{\text{high}}}$$

- No spin – only phase space

- Recall definition

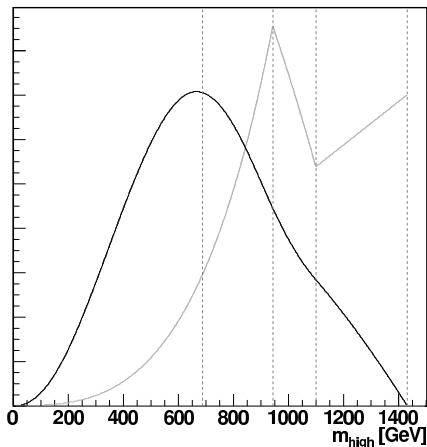
$$m_{\text{high}} \equiv \max\{m_{ac}, m_{bc}\}$$



The m_{high} Distribution - No Spin

m_D	m_C	m_B	m_A
2000	800	500	400

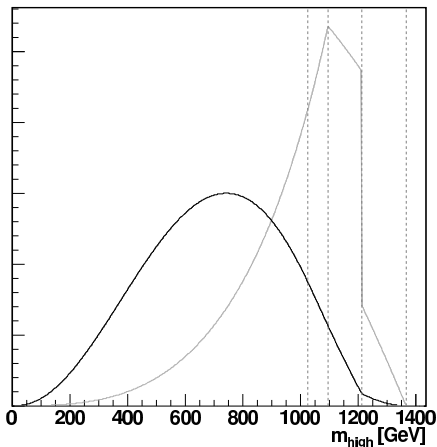
- Strong shape dependence on $(m_C - m_B)$ and $(m_B - m_A)$
 - m_D only sets scale
- Rich structure due to composite nature of m_{high}
 - note endpoint ‘foot’
- m_τ negligible unless m_A, m_B, m_C are close to degenerate



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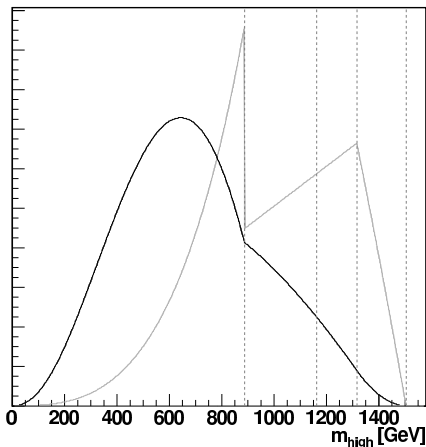
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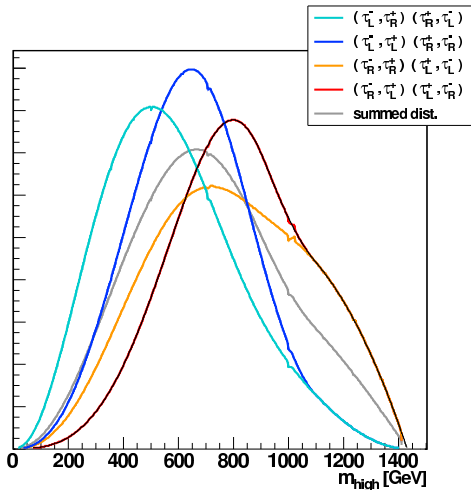
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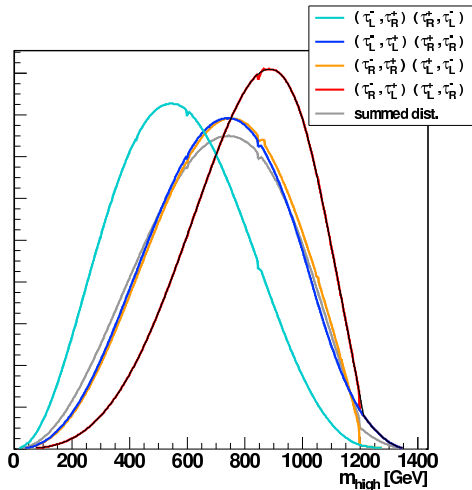
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- Splits into four distinct distributions
- One complete analytical result so far (thin black dist.)



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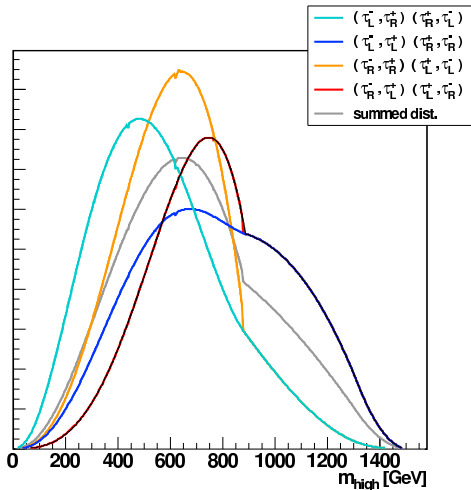
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Conclusions and Outlook

- Main result: The actual analytical expressions
(not shown explicitly here due to complicated form)
- Distribution shapes depend strongly on tau handedness
(stau and neutralino mixing)
- Strong dependence on mass scenario for m_{high}
 - promising for complete shape fit
- Further work:
 - Derive remaining shape formulas
 - Compare shapes to simulated data
 - Investigate deviations due to cuts, detector effects, etc

Thank you

Backup slides

General Method

- Method developed in
[Miller, Osland, Raklev, hep-ph/0510356]
– adapted for the ‘ditau topology’
- Start from variables with known distributions

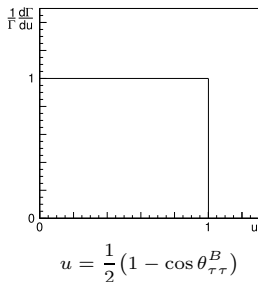
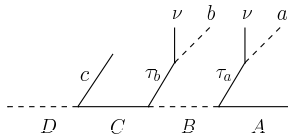
$$\frac{1}{\Gamma} \frac{d^3\Gamma}{du dv dw} = g(u, v, w)$$

- Kinematics

$$m^2 = h(u, v, w; \text{sparticle masses})$$

- Variable changes and integrations

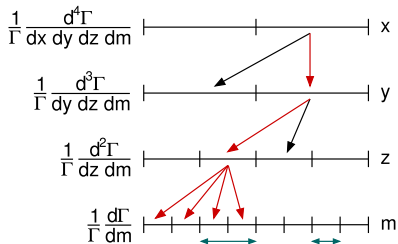
$$\frac{1}{\Gamma} \frac{d\Gamma}{dm^2} = \iint \left| \frac{\partial(u, v, w)}{\partial(u, v, m^2)} \right| \frac{1}{\Gamma} \frac{d^3\Gamma}{du dv dw} du dv$$



Main Difficulty

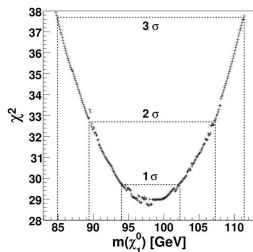
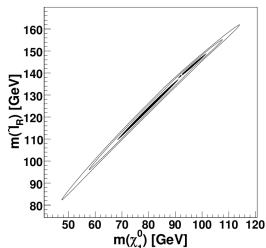
Main difficulty of the derivations:

- All possible integration regions must be covered
- 2- or 3-dimensional regions with complicated structure
- Expressions ‘fraction’ for each integration
- Order of final m regions shift with sparticle mass scenarios
- In sum: lots of bookkeeping!



Multiple Solutions

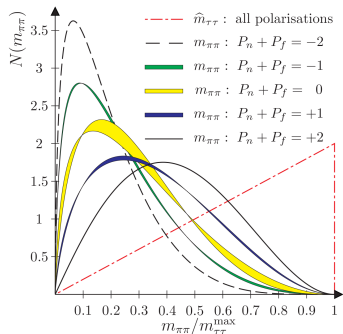
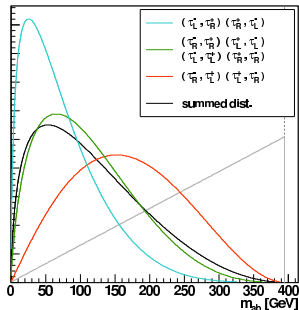
- One set of endpoints may be consistent with several sets of sparticle masses
- In some scenarios, endpoints are linearly dependent
- Need extra information
- Fits of analytical shape formulas can provide this information



[Gjelsten, Miller, Osland, Raklev, hep-ph/0611259]

The m_{ab} Distribution

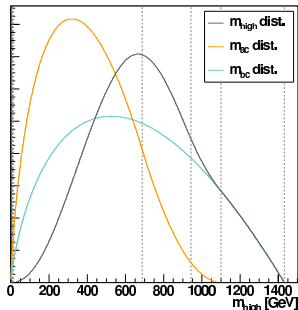
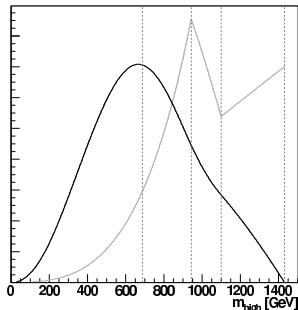
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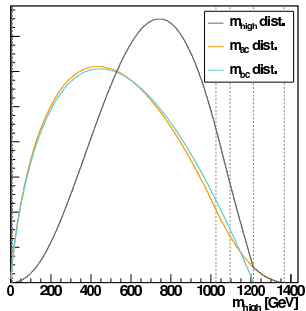
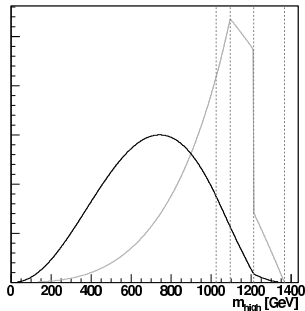
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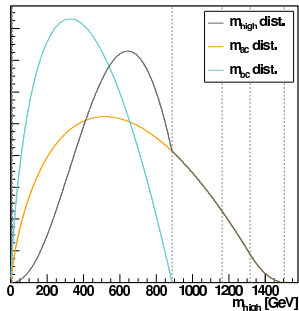
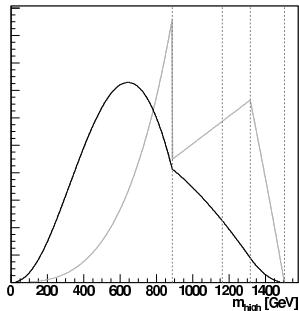
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